# Effective parameter inference for a mathematical model of the left ventricle

**RSS Glasgow** 

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Joint with: Dirk Husmeier, Hao Gao and Xiaoyu Luo

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University of Glasgow

#### Plan

## Background

The mathematical model

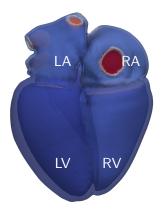
Statistical emulation

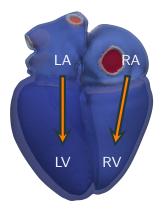
Emulation for multiple geometries

Parameter inference for different geometries

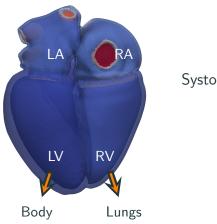
Using ex-vivo information

Ongoing work

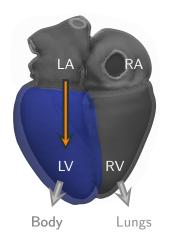




Diastole

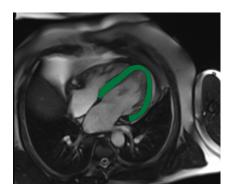


Systole

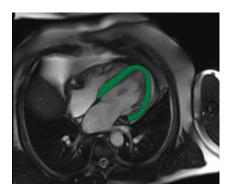


Our interest: left ventricle in diastole

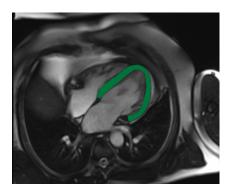
- Left ventricle function is guided by the myocardium.
- Relaxation of the muscle—passive behaviour— allows filling in diastole.
- With diastolic heart failure this filling reduces.
- Inferring the stiffness properties of the myocardium could help identify disease.



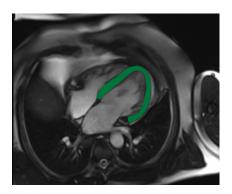
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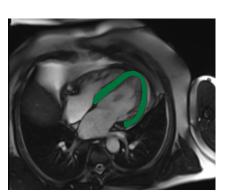
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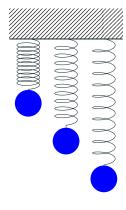


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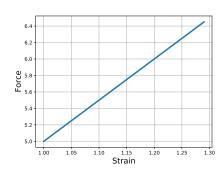


## Describing material behaviour



$$F = kx$$

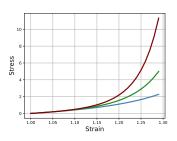
- Hooke's law is the stress-strain relation for linear materials.
- Describes the behaviour of the spring under external force.
- k is the material property—stiffness of the spring



## Parameterized description of left ventricle passive behaviour

- Stress strain relation for myocardium provided by the Holzapfel Ogden law.
- A parameterized description of the myocardium.
- Parameters give us the stiffness properties!

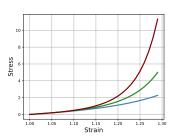
$$\begin{split} \boldsymbol{\Psi} &= \frac{a}{2b} \left[ \exp \left\{ b \left( \textit{I}_{1} - 3 \right) \right\} - 1 \right] \\ &+ \sum_{i \in \left\{ f, s \right\}} \frac{a_{i}}{2b_{i}} \left[ \exp \left\{ b_{i} \left( \textit{I}_{4i} - 1 \right)^{2} \right\} - 1 \right] \\ &+ \frac{a_{fs}}{2b_{fs}} \left\{ \exp \left( b_{fs} \textit{I}_{8fs}^{2} \right) - 1 \right\} \end{split}$$



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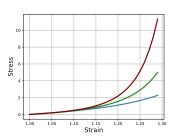
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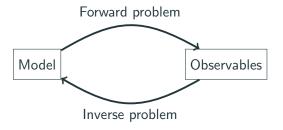
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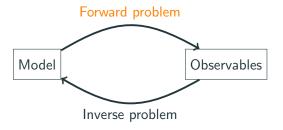
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## Forward and inverse problems



## Forward and inverse problems



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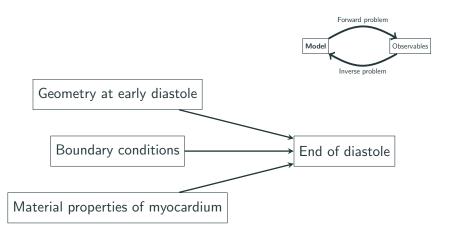
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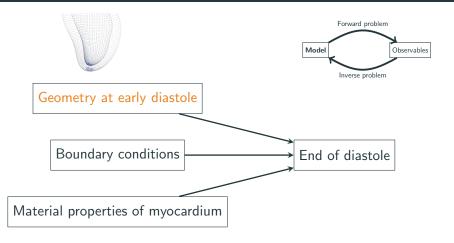
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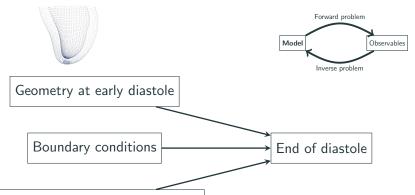
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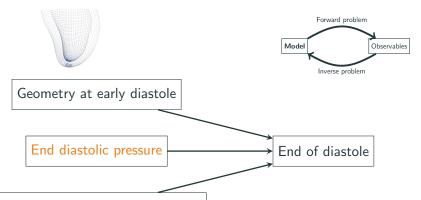






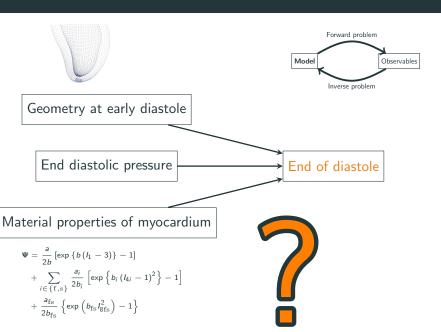
## Material properties of myocardium

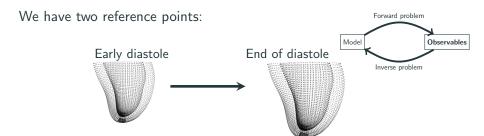
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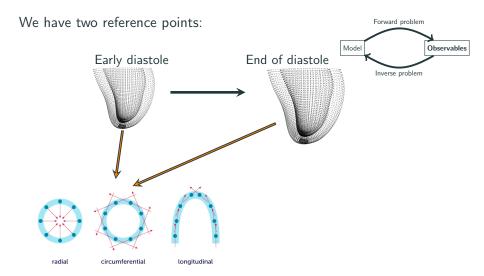


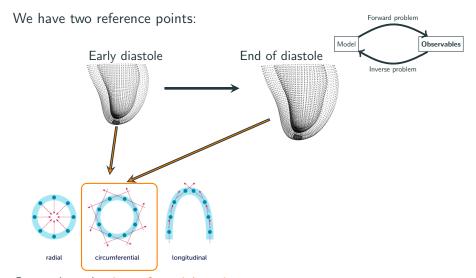
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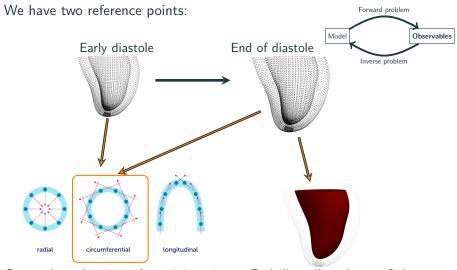








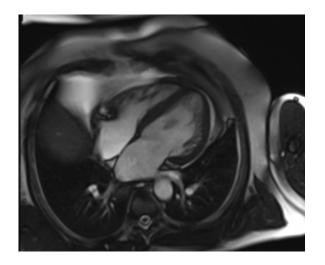
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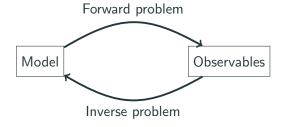
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End diastolic volume of the cavity.

## How are strains and volume measured?

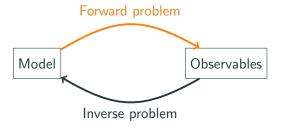


## Can we now solve the inverse problem?



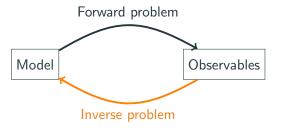
## Can we now solve the inverse problem?

## Expensive!



## Can we now solve the inverse problem?

## Very expensive!



We can solve if the patient can wait 2 days and we ignore our uncertainty...

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Emulation for multiple geometries

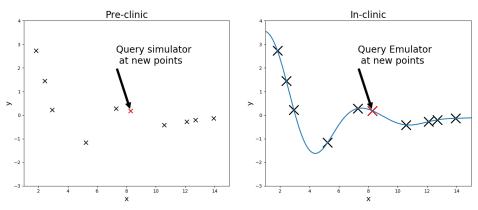
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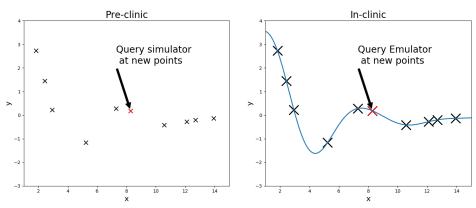
Move the expensive simulations to the pre-clinic phase.



**Two questions**: what is our input space and how do we obtain our emulator?

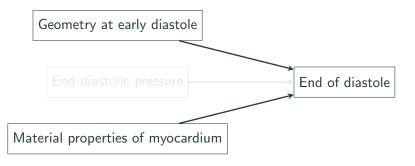
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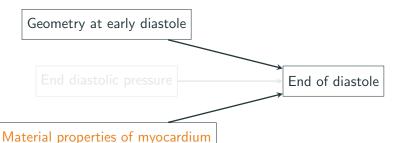


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#### Where do we run our simulator?



Geometry at early diastole

End diastolic pressure

End of diastole

# Material properties of myocardium

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Need to fill a 17k+8 dimensional space...

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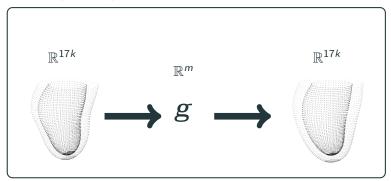
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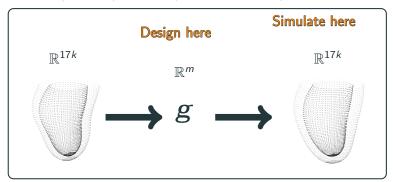
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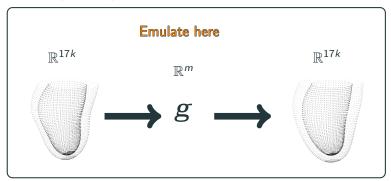
- Dimensionality reduction allows us to find a low dimensional representation of the LV geometry from n training left ventricles.
- Design in the low dimensional space and run the simulator on the reconstructed geometries
- These can be fully represented by the *m* dimensional projection.
- For our data (small n) PCA outperforms more sophisticated methods.



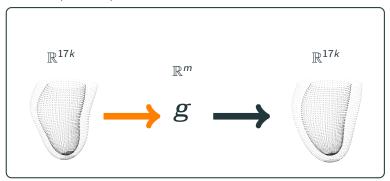
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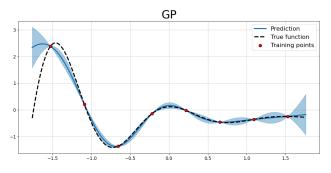
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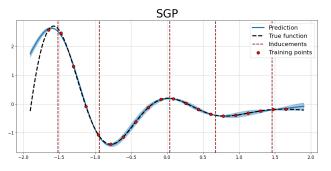
## The problem with GPs

- Gaussian processes are the standard models used for emulation.
- With large datasets they rely on approximations.
- Computational costs are only as low as the number of inducement points.
- Neural networks are parametric: prediction costs do not grow with training set size.



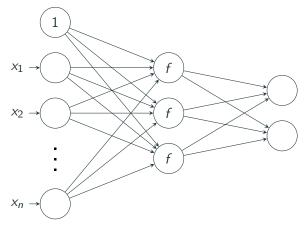
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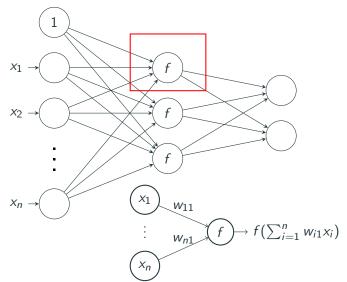
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Standard network architecture.

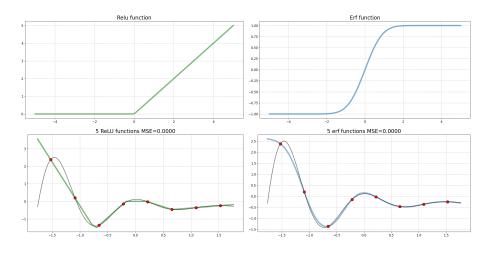


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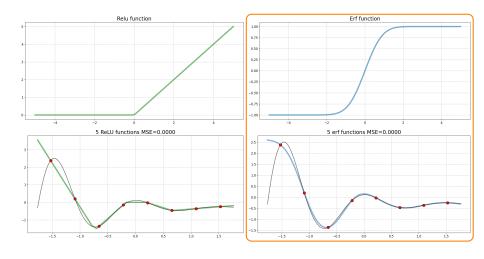
Standard network architecture.



### **Effect of activation function**



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Need to fill an m + 8 dimensional space...



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Tractable, but can we do better?

## A further reduction in complexity

$$\begin{split} \Psi &= \frac{\textit{a}}{2\textit{b}} \{ \exp[\textit{b}(\textit{I}_1 - 3)] - 1 \} + \sum_{\textit{i} \in \{\textit{f}, \textit{s}\}} \frac{\textit{a}_\textit{i}}{2\textit{b}_\textit{i}} \{ \exp[\textit{b}_\textit{i}(\textit{I}_{4\textit{i}} - 1)^2] - 1 \} \\ &+ \frac{\textit{a}_{\mathsf{fs}}}{2\textit{b}_{\mathsf{fs}}} [\exp(\textit{b}_{\mathsf{fs}}\textit{I}_{\mathsf{8fs}}^2) - 1] + \frac{1}{2} \end{split}$$

$$a = \theta_1 a_0,$$
  $b = \theta_1 b_0$   
 $a_f = \theta_2 a_{f0},$   $a_s = \theta_2 a_{s0}$   
 $b_f = \theta_3 b_{f0},$   $b_s = \theta_3 b_{s0}$   
 $a_{fs} = \theta_4 a_{fs0},$   $b_{fs} = \theta_4 b_{fs0}$ 

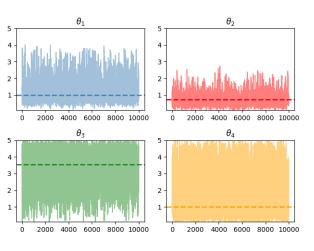
Infer  $\theta_1, \theta_2, \theta_3$  and  $\theta_4$ 

Emulation problem is now m + 4 dimensional

### **Sampling with MCMC**

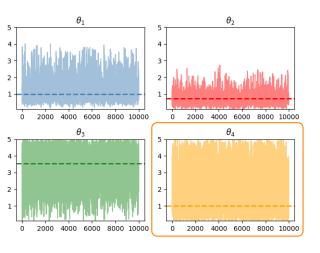
- We will use MCMC to quantify our uncertainty about the parameters.
- Two properties of the statistical emulator allow sampling with more sophisticated MCMC procedures:
  - Efficiency: prediction in order of milliseconds instead of 8 minutes.
  - 2. Differentiability of the function
- However, we use an approximation (emulator) of the true function.
- Error is compounded by our approximation of the geometry.
- How does this affect our inference?

# Inferring material parameters of a real geometry



Inference time: 15 seconds

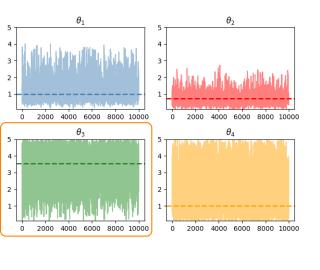
# Inferring material parameters of a real geometry



Circumferential strains and volume are not sensitive to  $\theta_4$ 

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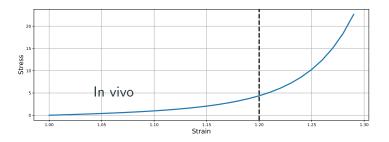
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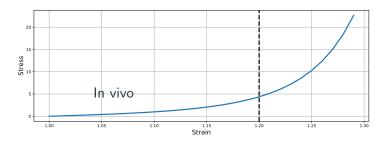


Inference time: 15 seconds

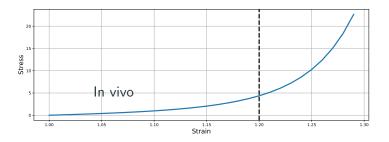
- Myocardium is a complicated material.
- Different components in material take effect at different stretches.
- Parameters of HO law reflect this changing behaviour
- Observed data are only informative about small stretch regime.



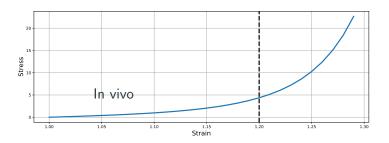
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The mathematical model

Statistical emulation

Emulation for multiple geometries

Parameter inference for different geometries

Using ex-vivo information

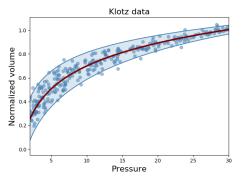
Ongoing work

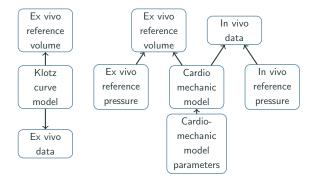
#### The Klotz curve

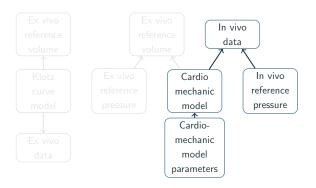
- Klotz et al inflated left ventricles (ex vivo) from volume  $V_0$  at pressure 0 to volume  $V_P$  and pressure P.
- Measuring also the volume at pressure 30,  $V_{30}$ , they found a relationship between normalized volume  $\tilde{V} = \frac{V_P V_0}{V_{30} V_0}$  and pressure P:

$$ilde{V} = rac{\log rac{P}{lpha}}{eta}$$

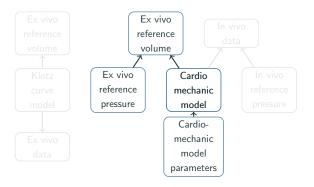
Can we use this relationship to include the behaviour at high stretch?



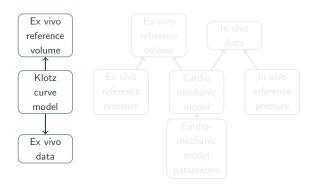




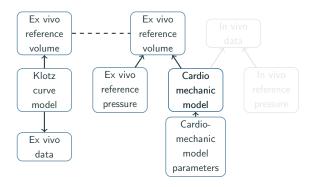
Our likelihood: this comes from our model of the in vivo left ventricle.



This distribution,  $\pi_E(\tilde{V}_{20})$ , comes from emulators trained to predict volume at pressure 20 and pressure 30 (with associated uncertainty).

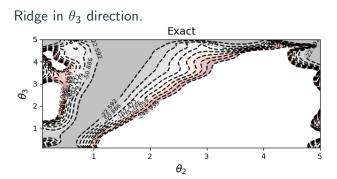


This distribution,  $\pi_{KL}(\tilde{V}_{20})$ , comes from enforcing the Klotz relationship on the left ventricle.

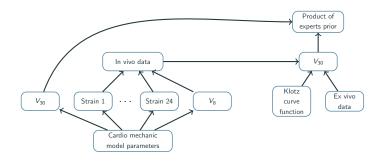


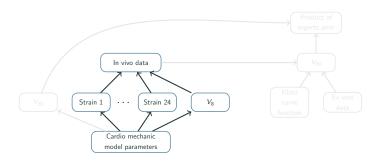
Match these with **product of experts**:  $\mathcal{F} = \int \pi_E(\tilde{V}_{20}) \pi_{\mathsf{KL}}(\tilde{V}_{20}) d\tilde{V}_{20}$ .

## Problem with the non empirical Klotz prior

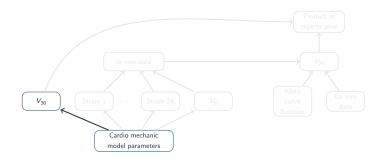


Let us try an alternative formulation...

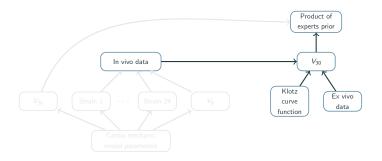




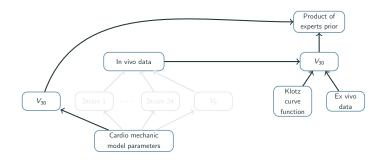
Likelihood function for in vivo data comes from emulated cardiac model.



A prediction of  $V_{30}$  comes from a pressure 30 volume emulator.

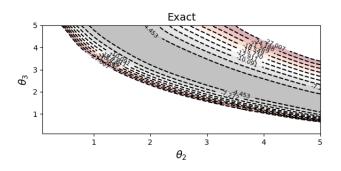


A prediction of volume at pressure 30 from Klotz function, this time related to the in vivo volume measurement.



Match with product of experts: now we have an empirical Klotz prior (relies on the measured volume)

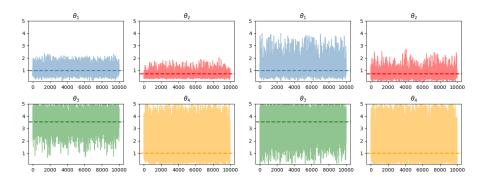
## Assessing performance of the Klotz prior



Ridge in the prior is aligned with the  $\theta_2$  axis.

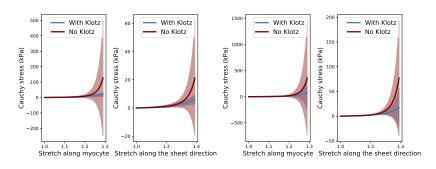
#### Does Empirical Klotz make a difference?

Yes, if our data are generated in line with the Klotz curve



But we do not know how closely the in vivo heart follows the Klotz curve

#### How about real data?



#### Summary so far

- The parameters from the reparameterized HO law are difficult to estimate
- Klotz is probably not the answer to the problem—do we really want to rely so heavily on ex vivo data?
- Instead, we should try new parameterizations
- Or accept lack of identifiability and try to use only those parameters we can learn

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#### Alternative parameterization

$$egin{aligned} \Psi &= rac{a}{2b} \left[ \exp \left\{ b \left( I_1 - 3 
ight) \right\} - 1 
ight] \ &+ \sum_{i \in \left\{ \mathrm{f,s} \right\}} rac{a_i}{2b_i} \left[ \exp \left\{ b_i \left( I_{4i} - 1 
ight)^2 \right\} - 1 
ight] \ &+ rac{a_{\mathrm{fs}}}{2b_{\mathrm{fs}}} \left\{ \exp \left( b_{\mathrm{fs}} I_{\mathrm{8fs}}^2 
ight) - 1 
ight\} \end{aligned}$$

 $a, b, a_{\rm f}, b_{\rm f}$  inferred,  $a_{\rm s}, b_{\rm s}, a_{\rm fs}, b_{\rm fs}$  constant

a and  $a_f$  are more identifiable, can we use these for predicting tissue health?

# Thank you!

## **PC** performance

